High Contrast Imaging at the Photon Noise Limit with WFS-based PSF calibration

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Scientific Motivation

High contrast imaging is currently limited by speckle noise at small IWA. Speckle noise typically ~100x photon noise, scales poorly with exposure time.

Poor detection confidence: is this a speckle or a planet ?

What if we knew exactly what the stellar PSF is ? "exactly" = bias-free estimate with precision at least as good as photon noise.

Is it possible to derive PSF from WFS telemetry ?



HR8799 system (c,d,e) Subaru Telescope/SCExAO

Scientific Motivation: Representative Examples

	Space-4m-Earth-G2	Ground-30m-Earth-M4
Star	G2 at 8pc	M4 at 4pc
Bolometric luminosity $[L_{Sun}]$	1.000	0.0072
Planet orbital radius [au]	1.0	0.085
Maximum angular separation [arcsec]	0.125	0.021
Reflected light planet/star contrast	1.5e-10	2.1e-8
Telescope diameter [m]	4	30
Science spectral bandwidth	20%	20%
Central Wavelength	797 nm (I band)	1630 nm (H band)
Maximum angular separation $[\lambda/D]$	3.0	1.9
Efficiency	20 %	20~%
Total Exposure time	10 ksec	10 ksec
Star brightness	$m_I = 3.60$	$m_H = 5.65$
Photon flux in science band (star)	7.37e8 ph/s	$5.62\mathrm{e9}~\mathrm{ph/s}$
Photon flux in science band (planet)	0.11 ph/s	118 ph/s
Background surf. brightness [contrast]	3.5e-10 (zodi+exozodi)	1e-5 (starlight)
Background flux in science band	0.26 ph/s	56200 ph/s
Photon-noise limited SNR (10 ksec)	18.1	49.7
Post-processing timescale (SNR=10 at planet flux)	50 mn	$7 \mathrm{mn}$
WFS timescale (SNR=10 at background flux)	6 mn	$1.8 \mathrm{ms}$

With 1e-5 raw contrast, Earth-size habitable planet imaged at SNR=10 in 7mn with 30m aperture in H band

Challenge: Planet is still 500x fainter than starlight







Real-time control vs. post-processing: Latency and Noise





Solution Uniqueness

Input measurement space (WFS, Bright Field, LOWFS etc...)

Speckle field / Dark Hole space



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On-Sky Validation of Solution Uniqueness

Similar WFS \rightarrow similar PSF ? Similar PSF \rightarrow similar WFS ?

YES NO (except at null)





Focal Plane image @750nm





WFS→ PSF relationship can be learned on-the-fly

Improving WFS reference from Focal Plane Image (DrWHO)



Evolution of the on-sky PSF before running the algorithm, after the first iteration, and the after last iteration. Each image is 0.25 arcsec (40x40 pixels) across, acquired at λ = 750 nm, 30 sec exposure time (computed by co-addition of 15,000 frames acquired at 500 Hz)

$On-sky \ WFS \rightarrow PSF \ Derivation \ with \ Neural \ Net$



Credit: Barnaby Norris & Alison Wong

PSF Subtraction relies on WF & PSF Stability



Are statistical properties of WF stable over course of observation ?

Self-Calibration relies on Stability of WFS \rightarrow PSF Relationship



Are optics between WFS and science image stable over course of observation ?

Ideal Hardware Configuration keeps relationship between WFS and PSF <u>stable</u>



Speckle Calibration from Bright Field Starlight

WF Control Calibration



We focus here on CALIBRATION (blue arrows)

Can we reconstruct residual starlight from auxiliary wavefront sensors and cameras ?



Experimental validation (lab)

1550nm, 25nm BW, Lyot Coronagraph 7 kHz frame rate



Single Frame Residual is at RON+PHN Level



30x Gain in Speckle Variance Demonstrated

All frames 128-sample (N = 60,000)cluster DH area Input sensing area DH area : $\sigma^{2}_{all}/\sigma^{2}_{cluster} = 30.7$ Input sensing area : $\sigma_{all}^2/\sigma_{cluster}^2 = 35.7$

Average (dark removed)

Variance (RON+ PHN removed)

Optimizing Wavelength for Sensitivity

Short wavelength : better optical gain from intensity to OPD Red target: higher photon count at longer wavelength

Table 6 Optimal Wavefront Sensing Wavele	length - I	linear	Regime
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Spectral	Teff	Optimal	Photon flux ^b	Flux gain relative to			
Type	[K]	$\operatorname{Band}^{\mathrm{a}}$	$[m^{-1}.ms^{-1}]$	В	R	Н	
B0V	31500	U	1.08e10	2.14	12.06	1337.0	
A0V	9700	В	5.01e7	1.00	4.25	204.7	
F0V	7200	В	1.05e7	1.00	2.78	82.1	B-band WFS is 33.7x
G0V	5920	В	1.34e6	1.00	1.80	33.7	more efficient than H-
K0V	5280	В	3.26e5	1.00	1.33	17.6	band WFS
M0V	3850	R	$3.53\mathrm{e}4$	2.03	1.00	3.93	
M4V	3200	Ι	4.65e3	12.5	1.80	2.83	
M8V	2500	J	6.00e2	150.0	11.6	1.98	

^aOptimal bandwidth selected among standard astronomical spectral bands (U, B, R, I, J, H). Assumes fixed relative spectral bandwidth $d\lambda/\lambda$. Central wavelength listed; ^bAssuming 10% effective spectral band at optimal sensing wavelength, main sequence star at 10pc.

Integating WFS and "PSF" within the same optical chip

"Astrophotonics: The Rise of Integrated Photonics in Astronomy" Norris & Bland-Hawthorn. Optics and Photonics News (2019) https://www.osa-opn.org/home/articles/volume 30/may 2019/features/astrophotonics the rise of integrated photonics in/



Illustration by Phil Saunders

GLINT module @ Subaru/SCExAO





 Null output: starlight is almost completely removed by destructive interference, providing deep contrast.
→This is where planet light and spectra are extracted

- **Fringe tracking output**: Bright starlight interference efficiently encode residual small (nm-level) optical aberration
- →Feed this information in real-time to upstream deformable mirror for correction
- →Use this information to calibrate how much starlight is left in null outputs

"Scalable photonic-based nulling interferometry with the dispersed multi-baseline GLINT instrument" Martinod, Norris, Tuthill...Guyon et al. **Nature Communications (2021)** link: <u>https://www.nature.com/articles/s41467-021-22769-x</u>





GLINT – on-sky Alpha Boo

1.4 kHz frame rate



Credit: Barnaby Norris, Univ. Sydney

Interferometric WFS with FIRST instrument



Credit: S. Vievard and V. Deo

On-sky demonstration of interferometric WFS

 \rightarrow provides path to high sensitivity chromatic WF measurement

Conclusions

Self-calibrating high contrast imaging systems could eliminate speckle noise

- $\rightarrow\,$ Deeper detection limits, limited by photon noise in science images
- \rightarrow Reliable science data

Early on-sky experiments are encouraging, but there are tough challenges :

- Computation algorithms and speed in high-dimension space
- Hardware implementation: wavelength diversity, data acquisition speed, internal stability

Photonic solutions (Photonic Nulling chip, Lantern, Integrated Optics) seem wellsuited for achieving self-calibration:

- Small number of degrees of freedom
- Can be spectrally dispersed with high readout speed